sdmay18-17 MicroCART (Microprocessor Controlled Aerial Robotics Team)

Week 13 Report Reporting Period: 12/4/17 - 1/15/18

Team Members

Blake Pries -- Communications Lead Dane Larson -- Ground Station Lead Matthew Kelly -- Documentation Lead and Webmaster Tyler Imboden -- Quad Software Lead Jakub Hladik -- Test Lead Kyle Trost -- Team Lead Peter Thedens -- Repository Lead Austin Rohlfing -- Controls Lead

Summary of Progress this Report

Generals Tasks for entire team:

• Team meeting planning

Quad Software - Tyler and Kyle:

Summary for progress this report:

• Got Vivado project building, however not functioning correctly. I need to do some further testing

Pending Issues:

- Vivado build
 - Motors don't like the wave they are getting
 - Not communicating with Ground station

Plans for upcoming reporting period:

• Test and resolve issues being faced involving vivado build

Controls - Austin and Blake:

Summary for progress this report:

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Pending Issues:

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Plans for upcoming reporting period:

- Talk with Matt to set a plan for this semester.
- Go through the model files on Git and clean up unused files.

Testing - Peter and Jakub:

Summary for progress this report:

- Provided feedback to Ground Station documentation update merge request (Peter)
- Attempted to upgrade to the latest version of JSBSim (Jake)

Pending Issues:

• Upgrade to the latest version of JSBSim (Jake)

Plans for upcoming reporting period:

- Work more on Makefile documentation (Peter)
- Look at infinite loop tests (Peter)
- Find place for information received from Brendan (Peter)
- Sort through MATLAB files related to "DataAnalysisTool" (Peter)
- Finish upgrade to the latest version of JSBSim and start experimenting with control algorithms (Jake)

Ground Station - Matt and Dane:

Summary for progress this report:

- Sample adapter created and communication files created. (Matt and Dane)
- Backend modifications for changing trackables complete. (Matt)
- Backend modifications for communicating to adapters and quad almost complete. (Matt)

• CLI changes for multiple trackables complete. (Matt)

Pending Issues:

- With multiple Quads do we need an additional controller?
- (Quad Software) Does the Quad actually provide the access point (needed for dual Quad flight planning)?

Plans for upcoming reporting period:

- Further update backend modifications to support future expandability rather than just supporting crazyflie. (Matt)
- Fly crazyflie and quad together (video will be provided). (Matt and Dane)
- Start on GUI updates for these changes. (Matt and Dane)
- Make sure that VRPN updates are sent to both objects during flight. (Matt)

| Name | Role | Contribution | Hours worked | Total |
|-----------------|------------------------|---|-----------------|-------|
| Peter Thedens | Repository Lead | Provided comments on merge request | 3 | 78 |
| Austin Rohlfing | Controls Lead | Worked on fixing XSDK build errors w/ Kyle | 7 | 85 |
| Kyle Trost | Team Lead | Got XSDK building the vivado build correctly. Stated Vivado documentation. | 10 | 128 |
| Matt Kelly | Documentation Lead | Working on Backend changes to support adapters. | 12 | 107 |
| Dane Larson | Ground Station Lead | Continued work on adapter | 1 | 79 |
| Jakub Hladik | Test Lead | Tried to fix and emailed JSBSim's | 2 | 80 |

| | | creator to resolve compile issue of the newest version. | | |
|---------------|------------------------|---|---|----|
| Tyler Imboden | Quad Software Lead | Looking into manual assist mode from software perspective | 2 | 88 |
| Blake Pries | Communications Lead | Saw someone fly a quadcopter in Utah | 0 | 65 |